

# Computational Logic

## Logic Programming

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Logic Program:

```
father(abraham, isaac) ←  
mother(sarah, isaac) ←  
father(isaac, jacob) ←  
parent(X, Y) ← father(X, Y)  
parent(X, Y) ← mother(X, Y)  
grandparent(X, Z) ← parent(X, Y), parent(Y, Z)  
ancestor(X, Y) ← parent(X, Y)  
ancestor(X, Z) ← parent(X, Y), ancestor(Y, Z)
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Query:

$(\exists X)(\exists Y) \text{ancestor}(X, Y)?$

Answer:

Yes for  $X = \text{abraham}, Y = \text{isaac}; X = \text{sarah}, Y = \text{isaac};$   
 $X = \text{abraham}, Y = \text{jacob}.$

A *literal* is an atom or the negation of an atom. A *positive literal* is an atom. A *negative literal* is the negation of an atom.

A *rule* is a formula of the form

$$L_1 \vee \dots \vee L_m \leftarrow L_{m+1} \wedge \dots \wedge L_n$$

where  $0 \leq m \leq n$  and each  $L_i$ ,  $1 \leq i \leq n$ , is a literal.

The rule represents a (disjunctive) clause

$$(\forall x_1) \dots (\forall x_k)(L_1 \vee \dots \vee L_m \vee \sim L_{m+1} \vee \dots \vee \sim L_n)$$

where  $x_1, \dots, x_k$  are all variables occurring in  $L_1, \dots, L_n$ .

A *logic program* is a finite set of rules.

# Definite Logic Program

A *definite rule* is a rule of the form

$$A_0 \leftarrow A_1 \wedge \cdots \wedge A_n$$

where  $0 \leq n$  and each  $A_i$ ,  $0 \leq i \leq n$ , is an atom.

A *definite logic program* is a finite set of definite rules.

$P \models (\exists x_1) \dots (\exists x_k)(A_1 \wedge \cdots \wedge A_n)$ ?

Is  $P \cup \{(\forall x_1) \dots (\forall x_k)(\neg A_1 \vee \cdots \vee \neg A_n)\}$  unsatisfiable?

Is  $P \cup \{\leftarrow A_1 \wedge \cdots \wedge A_n\}$  unsatisfiable?

A *definite goal* is a goal of the form

$$\leftarrow A_1 \wedge \cdots \wedge A_n$$

where  $0 \leq n$  and each  $A_i$ ,  $1 \leq i \leq n$ , is an atom.

$$\begin{aligned} p(c, Y, Y) &\leftarrow \\ p(f(X), Y, Z) &\leftarrow p(X, f(Y), Z) \end{aligned}$$

- domain  $\mathbb{N}$
- signature  $(\{c, f\}, \{p\}, \{c \mapsto 0, f \mapsto 1, p \mapsto 3\})$
- interpretation  $I_1$ 
  - $c^I = 0$
  - $f^I(x) = x + 1$
  - $p^I(x, y, z) \Leftrightarrow z = x + y$
- interpretation  $I_2$ 
  - $c^I = 1$
  - $f^I(x) = 2 * x$
  - $p^I(x, y, z) \Leftrightarrow z = 2^{x+y}$

# Herbrand Interpretation

A term is *ground* if it does not contain variables. Similarly, a formula is *ground* if it does not contain variables.

The *Herbrand universe*  $\mathcal{U}$  is the set of all ground terms. Similarly, the *Herbrand base*  $\mathcal{B}$  is the set of all ground atoms.

The *Herbrand interpretation* is an interpretation given by the following:

- 1 The domain is the Herbrand universe
- 2 If  $f$  is a function symbol with arity  $n$ , then
$$f^I = (t_1, \dots, t_n) \mapsto f(t_1, \dots, t_n)$$

# Example

$$\begin{aligned} p(c, Y, Y) &\leftarrow \\ p(f(X), Y, Z) &\leftarrow p(X, f(Y), Z) \end{aligned}$$

- domain  $\mathcal{U} = \{c, f(c), f(f(c)), f(f(f(c))), \dots\}$
- signature  $(\{c, f\}, \{p\}, \{c \mapsto 0, f \mapsto 1, p \mapsto 3\})$
- interpretation  $I$ 
  - $c^I = c$
  - $f^I(x) = f(x)$
  - $p^I(x, y, z) \Leftrightarrow x = f^a(c) \wedge y = f^b(c) \wedge z = f^{a+b}(c)$

We will denote Herbrand interpretation as the set of all satisfied grounded atoms.

An interpretation  $I$  is a *model* of a logic program  $P$  iff each rule in  $P$  is satisfied by  $I$ .

A logic program is satisfiable iff it has a Herbrand model.

Proof:

If  $I$  is a model of  $P$ , then

$$I' = \{p(t_1, \dots, t_n) \in \mathcal{B} \mid I \models p(t_1, \dots, t_n)\}$$

is a Herbrand model of  $P$ .

Example:

$$S = \{p(a), (\exists x) \sim p(x)\}, \mathcal{U} = \{a\}, \mathcal{B} = \{p(a)\}$$



# Declarative Semantics for Definite Logic Programs

Let  $P$  be a definite logic program and  $\mathcal{M}$  be a non-empty set of Herbrand models of  $P$ . Then  $\bigcap_{M \in \mathcal{M}} M$  is a Herbrand model of  $P$ .

Every definite logic program  $P$  has the least Herbrand model (denoted  $M_P$ ).

Proof: The set of all Herbrand models is non-empty, because Herbrand base is a model of  $P$ . Therefore the intersection of all Herbrand models is the least model of  $P$ .

Let  $P$  be a definite logic program. Then  $M_P = \{A \in \mathcal{B}_P \mid P \models A\}$ .

Proof:  $P \models A$  iff  $P \cup \{\sim A\}$  is unsatisfiable iff  $P \cup \{\sim A\}$  has no Herbrand models iff  $\sim A$  is false w.r.t. all Herbrand models of  $P$  iff  $A$  is true w.r.t. all Herbrand models of  $P$  iff  $A \in M_P$ .

# Immediate Consequence Operator

Let  $P$  be a definite logic program. An *immediate consequence operator*  $T_P$  is defined as follows:

$$T_P(I) = \{A \in \mathcal{B}_P \mid A \leftarrow A_1 \wedge \dots \wedge A_n \in \text{Ground}(P), \{A_1, \dots, A_m\} \subseteq I\}$$

The iteration  $T_P \uparrow n$  is defined as follows:

$$\begin{aligned} T_P \uparrow 0 &= \emptyset \\ T_P \uparrow (n+1) &= T_P(T_P \uparrow n) \\ T_P \uparrow \omega &= \bigcup_{n < \omega} T_P \uparrow n \end{aligned}$$

Let  $M_P$  be the least model of  $P$ . Then  $M_P = T_P \uparrow \omega$ .

SLD-resolution  $\equiv$  Linear resolution with Selection function for Definite clauses.

Let  $G$  be a goal  $A_1 \wedge \dots \wedge A_k \wedge \dots \wedge A_m$  and  $r$  be a rule  $B_0 \leftarrow B_1 \wedge \dots \wedge B_n$ . We say that a goal  $G'$  is a *resolvent derived from  $G$  and  $r$  using  $\theta$*  if  $\theta$  is the most general unifier of  $A_k$  and  $B_0$  and  $G'$  has the form

$$\leftarrow (A_1 \wedge \dots \wedge A_{k-1} \wedge B_1 \wedge \dots \wedge B_n \wedge A_{m+1} \wedge \dots \wedge A_m)\theta.$$

A *SLD-derivation* of  $P \cup \{G\}$  is a (possibly infinite) sequence of goals  $G_0, \dots, G_i, \dots$ , where

- $G_0 = G$
- $G_{i+1}$  is obtained from  $G_i$  and a rule  $r_{i+1}$  from  $P$  using  $\theta_{i+1}$

A *successful derivation* ends in empty goal  $\leftarrow$ . A *failed derivation* ends in non-empty goal with the property that all atoms does not unify with the head of any rule. An *infinite derivation* is an infinite sequence of goals.

Let  $P$  be a definite logic program and  $G$  be a definite goal. An *answer for  $P \cup \{G\}$*  is a substitution for variables in  $G$ . An answer  $\theta$  for  $P \cup \{G\}$  is *correct* iff  $P \models (A_1 \wedge \dots \wedge A_n)\theta$  where  $G = \leftarrow A_1 \wedge \dots \wedge A_n$ .

Let  $P$  be a definite logic program and  $G$  be a definite goal  $G$ . Let  $G_0, \dots, G_n$  be a successful derivation using  $\theta_1, \dots, \theta_n$ . Then  $\theta_1 \dots \theta_n$  restricted to the variables of  $G$  is the *computed answer*.

Let  $P$  be a definite logic program and  $G$  be a definite goal. Then every computed answer for  $P \cup \{G\}$  is a correct answer for  $P \cup \{G\}$ .

Let  $P$  be a definite logic program and  $G$  be a definite goal. For every correct answer  $\theta$  for  $P \cup \{G\}$  there exists a computed answer  $\sigma$  for  $P \cup \{G\}$  and a substitution  $\gamma$  such that  $\theta = \sigma\gamma$ .

Let  $P$  be a definite logic program and  $G$  be a definite goal. Then  $P \cup \{G\}$  is unsatisfiable iff there exists a successful derivation of  $P \cup \{G\}$ .

Let  $M_P$  be the least model of a definite logic program  $P$ . Then  $M_P = \{A \in \mathcal{B}_P \mid P \cup \{\leftarrow A\} \text{ has a successful derivation}\}$ .