Lecture 5: Reasoning with DL 2-AIN-108 Computational Logic

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Definition (Negation normal form)

A concept C is in negation normal form (NNF) iff the complement constructor (\neg) only occurs in front of atomic concept symbols inside C.

Preliminaries (cont.)

Lemma

For every concept C there exists C' in NNF such that $C \equiv C'$.

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Proof.

We can always "push" – inwards:

- $\neg (E \sqcap F) \equiv \neg E \sqcup \neg F$
- $\neg(E \sqcup F) \equiv \neg E \sqcap \neg F$
- $\neg \exists R.E \equiv \forall R.\neg E$
- $\neg \forall R.E \equiv \exists R.\neg E$

Since each C of finite length we eventually end up with C' in NNF. By structural induction C and C' are equivalent. \Box

Definition $(nnf(\cdot))$

Given any concept C, we denote by nnf(C) a concept C' in NNF s.t. $C \equiv C'$.

Definition (Finite interpretations)

An interpretation $(\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ is finite iff $\Delta^{\mathcal{I}}$ is a finite set.

Definition (Tree-shaped interpretations)

An interpretation $(\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ is tree-shaped iff (V, E), where $V = \Delta^{\mathcal{I}}$ and $E = \{ \langle x, y \rangle \mid (\exists R \in N_{\mathsf{R}}) \langle x, y \rangle \in R^{\mathcal{I}} \}$, is a tree.

Definition (Finite model property)

A DL \mathcal{L} is said to have finite model property iff for every satisfiable concept C that can be constructed in \mathcal{L} there exists a finite interpretation \mathcal{I} s.t. $C^{\mathcal{I}} \neq \emptyset$.

Definition (Tree model property)

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Theorem

ALC has the finite tree model property.

Corollary

 \mathcal{ALC} has the finite model property and the tree model property.

Definition (Completion tree)

A completion tree (CTree) is a triple $T = (V, E, \mathcal{L})$ where (V, E) is a tree and \mathcal{L} is a labeling function s.t.

- $\mathcal{L}(x)$ is a set of concepts for all $x \in V$;
- $\mathcal{L}(\langle x, y \rangle)$ is a set of roles for all $\langle x, y \rangle \in E$.

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Definition (Successor, *R*-successor)

Given a CTree $T = (V, E, \mathcal{L})$ and $x, y \in V$ we say that:

- y is a successor of x iff $\langle x, y \rangle \in E$;
- y is an *R*-successor of x iff $\langle x, y \rangle \in E$ and $R \in \mathcal{L}(\langle x, y \rangle)$.

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Note: CTrees are representations of interpretations: V corresponds to $\Delta^{\mathcal{I}}$; $\mathcal{L}(x)$ are the concepts to which x belongs; and similarly for $\mathcal{L}(\langle x, y \rangle)$ and $\langle x, y \rangle$.

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Definition (Clash)

There is a clash in a CTree $T = (V, E, \mathcal{L})$ iff for some $x \in V$ and for some concept C both $C \in \mathcal{L}(x)$ and $\neg C \in \mathcal{L}(x)$.

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Definition (Clash-free CTree)

A CTree $T = (V, E, \mathcal{L})$ is clash-free iff there if none of the nodes in V contains a clash.

Algorithm (Concept satisfiability)

Input: concept C in NNF Output: answers if C is satisfiable or not Steps:

- Initialize a new CTree $T := (\{s_0\}, \emptyset, \{s_0 \mapsto \{C\}\});$
- Apply tableau expansion rules (next slide) while at least one rule is applicable;
- Answer "C is satisfiable" if T is clash-free. Otherwise answer "C is unsatisfiable".

Tableau Algorithm for \mathcal{ALC} (cont.)

\mathcal{ALC} tableau expansion rules:

$$\begin{array}{ll} \sqcap \mathsf{-rule:} & \text{if } \mathcal{C}_1 \sqcap \mathcal{C}_2 \in \mathcal{L}(x), \ x \in V \ \text{and} \ \{\mathcal{C}_1, \mathcal{C}_2\} \nsubseteq \mathcal{L}(x) \\ & \text{then } \mathcal{L}(x) := \mathcal{L}(x) \cup \{\mathcal{C}_1, \mathcal{C}_2\} \end{array}$$

$$\begin{array}{ll} \square \text{-rule:} & \text{if } \mathcal{C}_1 \sqcup \mathcal{C}_2 \in \mathcal{L}(x), \ x \in V \text{ and } \{\mathcal{C}_1, \mathcal{C}_2\} \cap \mathcal{L}(X) = \emptyset \\ & \text{then either } \mathcal{L}(x) := \mathcal{L}(x) \cup \{\mathcal{C}_1\} \text{ or } \mathcal{L}(x) := \mathcal{L}(x) \cup \{\mathcal{C}_2\} \end{array}$$

$$\begin{array}{ll} \forall \text{-rule:} & \text{if } \forall R. C \in \mathcal{L}(x), \, x, y \in V, \, y \text{ } R \text{-successor of } x, \, C \notin \mathcal{L}(y) \\ & \text{then } \mathcal{L}(y) := \mathcal{L}(y) \cup \{C\} \end{array} \end{array}$$

 $\exists \text{-rule:} \quad \text{if } \exists R. C \in \mathcal{L}(x), x \in V \text{ with no } R \text{-successor } y \text{ s.t. } C \in \mathcal{L}(y) \\ \text{ then } V := V \cup \{z\}, \ \mathcal{L}(z) := \{C\} \text{ and } \mathcal{L}(\langle x, z \rangle) := \{R\}$

Tableau Algorithm for \mathcal{ALC} (cont.)

\mathcal{ALC} tableau expansion rules:

$$\begin{array}{ll} \sqcap \mathsf{-rule:} & \text{if } \mathcal{C}_1 \sqcap \mathcal{C}_2 \in \mathcal{L}(x), \ x \in V \ \text{and} \ \{\mathcal{C}_1, \mathcal{C}_2\} \nsubseteq \mathcal{L}(x) \\ & \text{then } \mathcal{L}(x) := \mathcal{L}(x) \cup \{\mathcal{C}_1, \mathcal{C}_2\} \end{array}$$

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$$\exists \text{-rule:} \quad \text{if } \exists R. C \in \mathcal{L}(x), x \in V \text{ with no } R \text{-successor } y \text{ s.t. } C \in \mathcal{L}(y) \\ \text{then } V := V \cup \{z\}, \ \mathcal{L}(z) := \{C\} \text{ and } \mathcal{L}(\langle x, z \rangle) := \{R\}$$

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Theorem (Correctness)

The tableaux algorithm for deciding satisfiability of concepts always terminates and it is sound and complete.

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The tableaux algorithm for deciding satisfiability of concepts always terminates and it is sound and complete.

For proof see:

- Attributive concept descriptions with complements. Schmidt-Schauß, M., Smolka, G. Artificial Intelligence 48(1):1-26, 1991
- *Description logics handbook.* Baader, F., et al., Cambridge University Press, 2003
- Semantic Investigations in Distributed Ontologies. Homola, M., PhD. thesis, Comenius University, 2010

$C \sqsubseteq D$ iff $\top \sqsubseteq \neg C \sqcup D$

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$$C \sqsubseteq D \ iff \top \sqsubseteq \neg C \sqcup D$$

Idea:

• To assure $\mathcal{I} \models C \sqsubseteq D$ we may instead assure that $x \in (\neg C \sqcup D)^{\mathcal{I}}$ for every $x \in \Delta$

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$$C \sqsubseteq D \ iff \top \sqsubseteq \neg C \sqcup D$$

Idea:

- To assure $\mathcal{I} \models C \sqsubseteq D$ we may instead assure that $x \in (\neg C \sqcup D)^{\mathcal{I}}$ for every $x \in \Delta$
- Add $\operatorname{nnf}(\neg C \sqcup D)$ to $\mathcal{L}(x)$ for every $x \in V$

$$C \sqsubseteq D \ iff \top \sqsubseteq \neg C \sqcup D$$

Idea:

- To assure $\mathcal{I} \models C \sqsubseteq D$ we may instead assure that $x \in (\neg C \sqcup D)^{\mathcal{I}}$ for every $x \in \Delta$
- Add $nnf(\neg C \sqcup D)$ to $\mathcal{L}(x)$ for every $x \in V$
- $\begin{array}{ll} \mathcal{T}\text{-rule:} & \text{if } C_1 \sqsubseteq C_2 \in \mathcal{T}, \ x \in V \ \text{and} \ \mathrm{nnf}(\neg C_1 \sqcup C_2) \notin \mathcal{L}(x) \\ & \text{then } \mathcal{L}(x) := \mathcal{L}(x) \cup \{\mathrm{nnf}(\neg C_1 \sqcup C_2)\} \end{array}$

Problem: naive use of \mathcal{T} -rule may lead to infinite looping:

• Let
$$\mathcal{T} = \{ \mathcal{C} \sqsubseteq \exists R. \mathcal{C} \}$$

• Is C satisfiable w.r.t. \mathcal{T} ?

Definition (Blocking)

Given a CTree $T = (V, E, \mathcal{L})$, a node $x \in V$ is blocked if it has an ancestor y such that

- either $\mathcal{L}(x) \subseteq \mathcal{L}(y)$;
- or y is blocked.

ALC Tableaux Expansion Rules for TBoxes

- $\begin{array}{ll} \sqcap \text{-rule:} & \text{if } C_1 \sqcap C_2 \in \mathcal{L}(x), \, x \in V \text{ and } \{C_1, C_2\} \nsubseteq \mathcal{L}(x) \\ & \text{and } x \text{ is not blocked} \\ & \text{then } \mathcal{L}(x) := \mathcal{L}(x) \cup \{C_1, C_2\} \end{array}$
- $\begin{array}{ll} \forall \text{-rule:} & \text{if } \forall R.C \in \mathcal{L}(x), \, x, y \in V, \, y \text{ } R \text{-successor of } x, \, C \notin \mathcal{L}(y) \\ & \text{ and } x \text{ is not blocked} \\ & \text{ then } \mathcal{L}(y) := \mathcal{L}(y) \cup \{C\} \end{array}$
- $\exists \text{-rule:} \quad \text{if } \exists R.C \in \mathcal{L}(x), x \in V \text{ with no } R \text{-successor } y \text{ s.t. } C \in \mathcal{L}(y) \\ \text{and } x \text{ is not blocked} \\ \text{then } V := V \cup \{z\}, \ \mathcal{L}(z) := \{C\} \text{ and } \mathcal{L}(\langle x, z \rangle) := \{R\}$
- $\begin{aligned} \mathcal{T}\text{-rule:} & \text{if } C_1 \sqsubseteq C_2 \in \mathcal{T}, \ x \in V \text{ and } \mathsf{nnf}(\neg C_1 \sqcup C_2) \notin \mathcal{L}(x) \\ & \text{and } x \text{ is not blocked} \\ & \text{then } \mathcal{L}(x) := \mathcal{L}(x) \cup \{\mathsf{nnf}(\neg C_1 \sqcup C_2)\} \end{aligned}$

Algorithm (Concept satisfiability w.r.t. TBox)

Input: concept C and T in NNF Output: answers if C is satisfiable w.r.t. T or not Steps:

- Initialize a new CTree $T := (\{s_0\}, \emptyset, \{s_0 \mapsto \{C\}\});$
- Apply tableau expansion rules for TBoxes while at least one rule is applicable;
- Answer "C is satisfiable w.r.t. *T*" if *T* is clash-free.
 Otherwise answer "C is unsatisfiable w.r.t. *T*".

Theorem (Correctness)

The tableaux algorithm for deciding satisfiability of concepts w.r.t. a TBox always terminates and it is sound and complete.

Idea: Encode \mathcal{A} into the CTree

If a : C ∈ A
a^T ∈ C^T in every model I
add node a into T
add C into L(a)
If a, b : R ∈ A
⟨a^T, b^T⟩ ∈ R^T in every model I
add nodes a, b into T
add R into L(⟨a, b⟩)

Idea: Encode \mathcal{A} into the CTree

Note: T is no longer necessarily a tree

Algorithm (Concept satisfiability w.r.t. TBox and ABox)

Input: concept C and $\mathcal{K} = (\mathcal{T}, \mathcal{A})$ in NNF Output: answers if C is satisfiable w.r.t. \mathcal{K} or not Steps:

• Initialize a CTree T as follows:

- V := {a | constant a occurs in A} ∪ {s₀};
 E := {⟨a, b⟩ | a, b : R ∈ A for some role R};
 L(a) := {nnf(E) | a : E ∈ A} for all a ∈ V;
 L(⟨a, b⟩) := {R | a, b : R ∈ A} for all ⟨a, b⟩ ∈ E;
 L(s₀) := {C}
- Apply tableau expansion rules for TBoxes while at least one rule is applicable;
- Answer "C is satisfiable w.r.t. K" if T is clash-free.
 Otherwise answer "C is unsatisfiable w.r.t. K".

Algorithm (Concept satisfiability w.r.t. TBox and ABox)

Input: concept C and $\mathcal{K} = (\mathcal{T}, \mathcal{A})$ in NNF Output: answers if C is satisfiable w.r.t. \mathcal{K} or not Steps:

Initialize a CTree T as follows:

- $V := \{a \mid constant \ a \ occurs \ in \ A\} \cup \{s_0\};$ • $E := \{\langle a, b \rangle \mid a, b : R \in A \ for \ some \ role \ R\};$ • $\mathcal{L}(a) := \{nnf(E) \mid a : E \in A\} \ for \ all \ a \in V;$
 - $\mathcal{L}(\langle a,b
 angle):=\{R\mid a,b:R\in\mathcal{A}\} ext{ for all } \langle a,b
 angle\in E;\ \mathcal{L}(s_0):=\{C\}$
- Apply tableau expansion rules for TBoxes while at least one rule is applicable;
- Answer "C is satisfiable w.r.t. K" if T is clash-free. Otherwise answer "C is unsatisfiable w.r.t. K".

Note: Same algorithm can be used to verify just the consistency of \mathcal{K} , simply omit generation of s_0 and its label during the initialization. $s_{0,0,0}$

Theorem (Correctness)

The tableaux algorithm for deciding satisfiability of concepts w.r.t. TBox and ABox always terminates and it is sound and complete.